

functionality down to the device level, while P2P GOS clusters have the potential of elevating the role of GOS into an all-encompassing data bank service solution on the grid.

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A Dynamic Estimation Scheme for Fault-Free Scheduling in Grid Systems

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he dynamism of grid computational environments, which resources can join and leave in an unpredictable fashion, allows for unprecedented growth in the Grid's capacity. At the same time, resource availability at any given moment is uncertain.

In work under way at the National University of Singapore, we've observed that most grids fall into one of two main categories:

- Planned and negotiated, in which the infrastructure is designed with resources committed to the grid.
- Dynamic and voluntary, in which the infrastructure operates in a peer-to-peer fashion with resources joining or leaving on no prearranged schedule.

This discrepancy makes it difficult to design robust and fault-tolerant scheduling algorithms for both resource categories. It also leads to difficulties in providing capabilities such as advanced reservations and quality-of-service assurances.

Figure 2 illustrates a resource lifecycle model to address this problem. It creates a series of time events and applies stochastic methods to the probability of each one occurring. Any scheduling algorithm can use this model to quantitatively estimate how many nodes would be online at a certain time. Algorithms can also use this model to determine the probability of a job completing its execution based on its required runtime and node allocation. This information helps allocate resources efficiently.

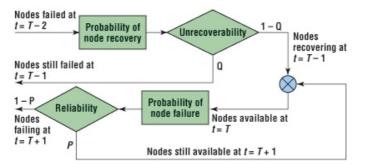


Figure 2. Resource lifecycle model describing the time window t that affects the number of nodes available at time T. P and Q describe the reliability and unrecoverability factors that modifies the basic MTTF and MTTR values.

Initial simulations based on this model have indicated prediction errors in the range of +/- 1 to +/- 2 CPUs in a Grid environment, when performed over a span 100 times longer then the mean time to failure (MTTF) values of the nodes.

Our next research objective is to incorporate this information in conventional scheduling algorithm heuristics over a homogeneous failure-prone environment and assess its effectiveness. We will then expand the work's scope to include large-scale heterogeneous distributed systems and grids.

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